

# **Micromanipulator System** NT-88=V3 Series

Photos courtesy of Masumi Hirabayashi, Associate professor, National Institute for Physiological Sciences Specimen1: Injection of rat's ES cell into 8-cell embryo Specimen2: Microinsemination of rat egg

Micromanipulators and related equipment other than microscopes are manufactured by:

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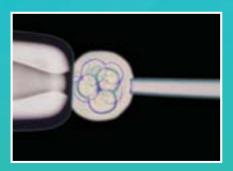
# **Fusion of Utmost Precision and Fine Mechanism**

ICSI (Intracytoplasmic sperm injection) and IMSI (Intracytoplasmic morphologically selected sperm injection), IVF (In vitro fertilization) technologies that have received a lot of attention in recent years as a remedy for male infertility, require a highly precise manipulator to respond to delicate movement of the operator's hands.

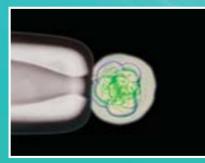
Stable, smooth manipulation is also required for injection to the stem cell, transgenics and electrophysiology.

The NT-88-V3 series, jointly developed by Nikon and Narishige, ensures easy operation and an unsurpassed level of precision. When used in combination with Nikon's high-performance microscopes, it provides strong support for cutting-edge biomedical research.

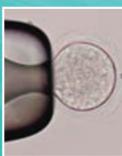
- Size is greatly reduced as the 3D motor-driven coarse control manipulator and 3D hydraulic fine micromanipulator are combined in a single unit.
- Assembly of the micromanipulator is fast and easy due to the extremely stable, one-piece mounting adapter.
- Wide varieties of microinjectors for holding or injecting specimens depending on use.















### **Oil-hydraulic Micromanipulators**

## 3D Hydraulic Micromanipulator NT-88-V3

Combined 3D motor-driven coarse control manipulator and the 3D hydraulic fine micromanipulator realize remarkably compact and stable design.

- Less than half the size of a conventional model—minimal length tubes and cords—the manipulator fits easily into the incubator.
- Closer-to-the-center settings are possible, while reduced distance from manipulator mount to microelectrode tip increases stability.
- X-axis control knobs are located symmetrically on opposite sides of the joystick to eliminate left side/right side positioning problems.
- 10mm X-Y operating range provides versatility in manipulation at lower magnifications.
- A "resume" feature returns the pipette to the original position after the pipette has been raised for quicker, easier Petri dish changes.
- The universal joint is outfitted with an angle gauge, which ensures accurate-angle operation. The forward-mounted return mechanism facilitates Petri dish changing.
- Permits one-touch installation on an inverted microscope.

Suitable for experiments that do not require the holding side's

pipette, such as the microinjection or microdissection to an







### 3D Hydraulic Micromanipulator (Manual Single-hand type) NT-88-V3MSH

**3D Hydraulic Micromanipulator** 

(Single-hand type)

adherent cell

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A manual 3D coarse positioning manipulator allows you to quickly move the micro-pipette to the ideal position. And the compact design allows you to position it closer to you with the control knob in easy reach.

		NT-88-V3	NT-88-V3SH	NT-88-V3MSH	
Hydraulic fine microm	anipulator				
Working range	Control knob operation	Max. 10mm			
	Joystick operation	Max. 2mm			
Displacement by	Full turn of knob	250µm			
control knob rotation	Minimum graduation	2µm			
Coarse manipulator					
Working range		Max. 22mm (motorized) Max. 30mm (ma		Max. 30mm (manual)	

# Universal Joint

Universal Joint UJ-V3 allows the pipette holder to be moved in a single direction. The angle can be adjusted for both vertical and horizontal directions via two separate control knobs. The forward-mounted return mechanism facilitates changing the petri dish while the built-in angle gauge ensures accurate-angle operation. Moreover, because the UJ-V3 is mountable from above, unlike the conventional type, attachment and removal is much easier.

### Oil-type Microinjector IM-9B Pneumatic Injector IM-9C

The IM-9B, which is suitable for injection, and the IM-9C, which is suitable for holding, provide smoother and more stable maneuverability by applying a new mechanism to minimize backlashes. Also, their 53mm working distance, large-volume syringe and just-the-right-size control knob with graduated scales all contribute to easy control of the injection. The IM-9B has a glass syringe for easy confirmation of internal air bubbles while its new tube connector with a three-way stopcock makes for easier filling of oil without generating air bubbles.

	IM-9B	IM-9C			
Movement distance					
Movement range	53mm	53mm			
Full rotation of knob	500µm	6mm			
Control value					
Full rotation of knob	Approx. 10µl	Approx. 480µl			
Syringe	1,060µl glass type	4,240µl metal type			

### Microscope Adapters for NT-88-V3

Various adapters are available for use with Nikon microscopes. As both adapters and manipulators are compact, attaching them is very easy.





NS-TEV3 Mounting Adapter to use with inverted microscopes Ti and TE2000

NS-T1 Mounting Adapter to use with inverted microscope TS100





#### Pipette Holder HI-7 with Rotating Mechanism HIR



The HI-7 pipette holder provides improved protection against oil leaks. Alignment of the pipette tip in the microscope field is now a simple procedure with the rotating mechanism HIR.



NS-SMV3 Mounting Adapter to use with stereoscopic microscope SMZ series It can be adapted to the diascopic stand of the SMZ series.



NS-FNV3 Mounting Adapter to use with fixed stage microscope FN1 Two adapters are necessary when mounting a micromanipulator on both sides.

### Micromanipulators for electro-physiology applications

# 3D Water-Hydraulic Micromanipulator MHW-3

The MHW-3 features minimized drift due to temperature changes, a scale increment as small as 0.2µm, and a fine control manipulation with a one-to-five moving ratio. Also, because Teflon tubes are secured to the microscope main body, vibration of the tip of the micropipettes has been eliminated, resulting in stable micromanipulation.

Movement range	Fine 2mm (X, Y and Z axes), coarse 30mm (X, Y and Z axes)
Full rotation of knob	50µm
Minimum graduation	Fine 0.2µm



MHW-3 with NN-L3 adapter, configured with patch amplifier

## 3D Motorized Micromanipulator

The MM-80 has been developed to satisfy the competing goals of "stability" and "compactness" that are essential for research work in electrophysiology.

The motorized micromanipulator is constructed in a simplified design with its controller employing simple-design push button switches. The drive unit embodies user-friendly convenient features which help reduce stress during experiments.

		Fine 20mm (X, Y and Z axes), coarse 30mm (X, Y and Z axes)		
Driving speed	Minimum	Approx. 10µm/s*		
(Motorized fine drive)	Maximum	Approx. 150µm/s*		

\* DC motor drive, theoretical value

# Manual 3D Micromanipulators

The NMN-21 and -25 are designed for drift-free operation, making them ideal for delicate, patch-clamp research. The unit has no hydraulic system nor spring mechanism and its unique double-slider structure minimizes vibrations transmitted from the operator's hand to the tip of the pipette via the control knob. The unit's motor-less and actuator-less design also eliminates electromagnetic disturbances. The NMN-25 features a compact, space-saving design without a scale.

	NMN-21	NMN-25
Movement range	Fine 6mm (X, Y and Z axes), coarse 15mm (X, Y and Z axes)	Fine 6mm (X and Z axes), coarse 15mm (X and Z axes), combined coarse and fine working range 15mm (Y axis)
Full rotation of knob	Fine 250µm, coarse approx. 4mm	Fine 250µm (X and Z axes), approx. 250µm (Y axis)
Minimum graduation	Fine 1µm	—





NMN-21

### Recommended combination for various applications

### For ICSI (Intracytoplasmic Sperm Injection), ES cell injection and nucleus transfer

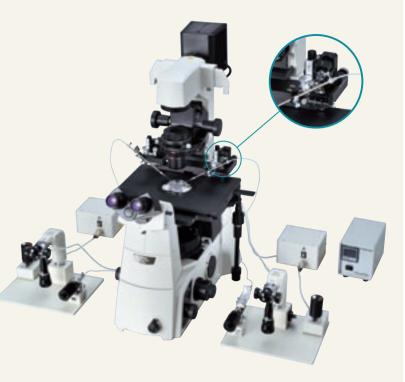
The microinjection system is dedicated to floating cell applications. The inner diameter of the pipette tip is more than  $5\mu$ m. For the injection of the sperm, embryo-stem cell and nucleus, a manual injector is suitable as it accurately transmits the movement of user's hand via the handle.

Product	Unit	Model name				
Components						
Microscope	1	Ti-U NAMC set				
3D hydraulic micromanipulator	1	NT-88-V3				
Microinjector (injection side)	1	IM-9B				
Pneumatic injector (holding side)	1	IM-9C				
Stage thermal control system: Thermo Plate	1	MATS-U505R30				
Options for making pipettes		•				
Puller	1	PC-10				
Microgrinder	1	EG-400				
Microforge	1	MF-900				
Glass capillaries	1	G-1				

#### For injection into adherent cells

The microinjection system for adherent cells incorporates a oneaxis oil hydraulic micromanipulator—it moves in the direction of a pipette—only on the injection side, since it does not require an injector on the holding side. A motorized injector that can accurately control the injection amount of DNA and fluorescence dyes is suitable.

Product	Unit	Model name				
Components						
Microscope	1	Ti-U DIC set				
3D hydraulic micromanipulator (single-hand type)	1	NT-88-V3SH				
Mounting adapter	1	NS-TEV3				
1D hydraulic micromanipulator	1	MMO-220A				
Motorized microinjector	1	IM-300				
Stage thermal control system: Thermo Plate		MATS-U505R30				
Options for making pipettes						
Puller	1	PC-10				
Glass capillaries	1	GD-1				





### Single-cell patch clamping with inverted microscope

This system is suitable for single-cell patch clamp experiments using an inverted microscope. Two units, one each for recording and stimulating, are included. A water-hydraulic micromanipulator effective for general manipulations is suitable.

Product	Unit	Model name			
Components					
Microscope	1	Ti-U DIC set			
Mounting adapter	1	NN-L3			
3D water-hydraulic micromanipulator	2	MHW-3			
Patch amplifier adapter*		AP-12A/L/N or			
		AP-13-2			
Options for making pipettes					
Puller	1	PC-10			
Microforge		MF-830			
Glass capillaries		GD-1.2			
Glass capillaries	1	GD-1.5			

\* Please select an adapter that suits the brand of patch amplifier used.



#### Manual patch clamping

This system is suitable for patch clamp experiments on slice cells using an upright microscope. The two stages that incorporate new functions were developed especially for the FN1. One is independent from the microscope and the other, a manual XY stage, enables the microscope's observation field to be changed. Though three waterhydraulic micromanipulators are used in the picture, any number can be selected.

Product	Unit	Model name			
Components					
Microscope	1	FN1-DIC set			
Stage	1	ITS-FN1			
3D water-hydraulic micromanipulator	3	MHW-3			
Patch amplifier adapter*	2**	AP-12A/L/N, AP-13-2			
Options for making pipettes					
Puller	1	PC-10			
Microforge	1	MF-830			
Glass capillaries	1	GD-1.2			
Glass capillaries	1	GD-1.5			

\* Please select an adapter that suits the brand of patch amplifier used.

\*\* Any one of the following combinations is possible: AP-12A/L/N x2, AP-13-2 x1, AP-12A/L/N x1 + AP-13-2 x2

### Single-cell patch clamping with upright microscope

This system is suitable for single-cell patch clamp experiments using an upright microscope. Two units, one each for recording and stimulating, are included. A water-hydraulic micromanipulator effective for general manipulations is suitable.

Product	Unit	Model name		
Components				
Microscope	1	FN1-DIC set		
Mounting adapter	1	NN-R		
3D water-hydraulic micromanipulator	2	MHW-3		
Patch amplifier adapter*	1	AP-12A/L/N or AP-13-2		
Options for making pipettes		•		
Puller	1	PC-10		
Microforge	1	MF-830		
Glass capillaries	1	GD-1.2		
Glass capillaries	1	GD-1.5		

\* Please select an adapter that suits the brand of patch amplifier used.



#### Blind patch clamping with stereoscopic microscope

This system uses a stereoscopic microscope for patch clamp experiments. A cost efficient water-hydraulic micromanipulator is suitable for this application.

Product	Unit	Model name				
Components						
Microscope	1	SMZ1500 diascopic, LWD set				
Mounting adapter	1	NN-T-2				
Water-hydraulic micromanipulator	1	MWS-1B				
Patch amplifier adapter*	1	AP-14A/L/N or AP-13-3				
Options for making pipettes						
Puller	1	PC-10				
Glass capillaries	1	GD-1.2				
Glass capillaries	1	GD-1.5				

\* Please select an adapter that suits the brand of patch amplifier used.





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### Accessories

### **Micropipette Puller PC-10**

The PC-10 is used to pull the glass capillary vertically, utilizing the gravitational force of its own weight. It has two modes: a single pull, pulling capillary at one stretch, and a double pull in which the setting is changed in mid-process. The versatile vertical pull type is suitable for both injection purposes and patch clamping.



### Microforge MF-830

A powerful microscope with 525x total magnification is incorporated to make electrodes with tips less than 2µm for patch clamping.



### Automatic Microscope Stage Thermal Control System Thermo Plate MATS-U505R30

The flat surface of the plate enables easy manipulator operation and specimen changes.

(Manufactured by Tokai Hit Co., Ltd.)



### **Pipette Grinder EG-400**

The grinder with minimized irregular movements of the grinding plane and the microscope are combined. Precise grinding while

confirming needle contact with grinding plane is facilitated.



### Microforge MF-900

The MF-900 is designed to produce injection and holding pipettes. In addition to the temperature and illumination, the position of the heating element can be adjusted.



### **Glass Capillaries G-1**

The general purpose glass capillary G-1 has been prewashed in an ultrasonic washing machine.

### Glass Capillaries with Filament GD-1, GD-1.2, GD-1.5

Commonly known as double tubing, these glass capillaries contain an internal glass fiber (approx. 100µm). GD-1 has been prewashed in an ultrasonic washing machine.

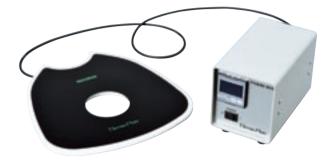


### Compatibility of patch amplifier adapters

		Manipulator/Patch amplifier adapter					
Headstage maker and model name		MHW-3	MM-80	NMN-21 NMN-25	MWS-1B	MHW-4	
AXON	HS-2						
	HS-4		AP-14A				
	VG-2						
	VG-2A	AP-12A					
	CV-4						
	CV-5						
	CV-202 (CV-201AU)						
	CV-203BU	AP-13-2	AP-13-2		13-3		
	CV-7A/B						
	HS-9A						
HEKA	EPC-7						
	EPC-8	AP-12L		AP-	14L		
	EPC-9						
	EPC-10	AP-13-2		AP-1	13-3		
Nihon	JZ-230J						
Kohden	JZ-240J	AP-12N		AP-	14N		
	JZ-245J						

### Automatic Microscope Stage Thermal Control System Thermo Plate MATS-USMZSL

It can be easily attached to the microscope by inserting it into the stage plate hole. As its shape fits the stage, the thermal control of the wide area of the specimen is possible. The flat surface of the plate enables easy manipulator operation and specimen changes. (Manufactured by Tokai Hit Co., Ltd.)





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